

AutoPar: Semantics-Aware Automatic Insertion of OpenMP Directives

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Motivation

- Future extreme-scale architectures will contain computation nodes with abundant parallelism provided by heterogeneous components (such as GPUs) in order to meet performance goals within power constraints.
 - ☐ Many existing High-Performance Computing (HPC) applications exploit only coarse-grain parallelism via MPI, leaving tens of thousands of serial inner loops. Very few of them support fine-grain threading exploiting GPUs.
- Existing parallelization tools mostly focus on Fortran or C applications.
 - ☐ Many LLNL applications are written in C++ with high-level abstractions represented as complex types : classes and templates ...
 - ☐ Rich semantics (meanings) are associated with these abstractions
 - $a \rightarrow foo(x)$: x is **read only** by a->foo()
 - *STL::vector<T>* : elements **stored contiguously**
 - Loop using iterators: semantically equal to a classic for loop using an integer loop variable
 - ☐ Traditional tools depending on conventional compilers using low level internal representation (IR)
 - ☐ Difficult to discover high-level abstractions
 - ☐ Even more challenging to extract/leverage associated semantics

Approach

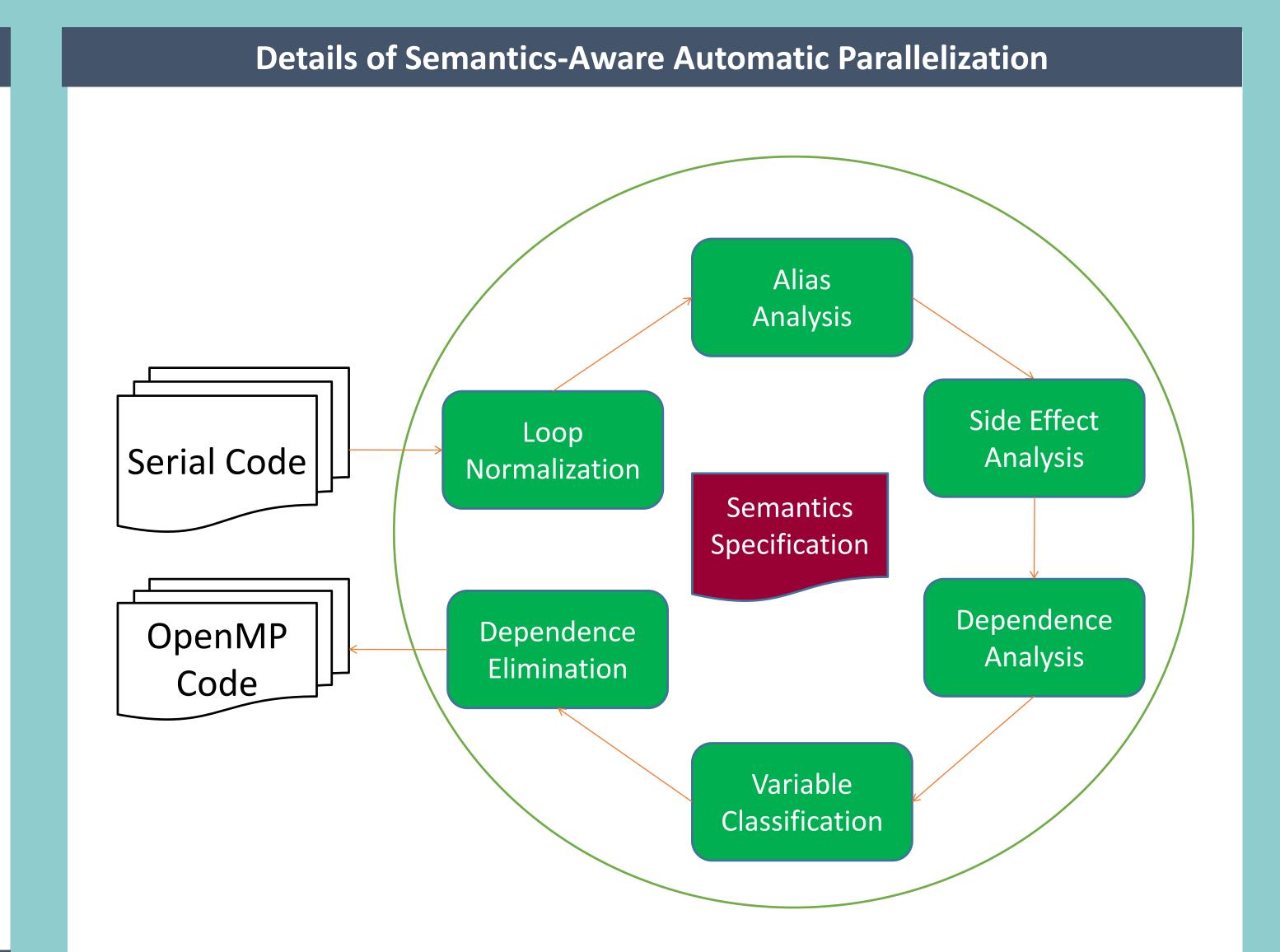
- Recognize high-level abstractions (complex C++ classes, templates, etc.) from Abstract Syntax Tree generated by the ROSE source-to-source compiler
- Encode application semantics via specification files
- Extend classic parallelization algorithms to exploit application semantics

```
class floatArray { // user defined array abstraction
    alias none; overlap none; //elements are alias-free and non-overlapping
    is_fixed_sized_array { //semantic-preserving functions as a fixed-sized array
    length(i) = {this.size()}; // array semantics: obtain length
    element(i) = {this.operator[](i); this.elem(i);}; // array element access semantics
    };
};

std::list<SgFunctionDef*> findCFunctionDefinition(SgNode* root){
    read {root}; modify {result}; //side effects of a function
    return unique; //return a unique set
}

operator pow(double val1, double val2)
    {
    modify none; read {val1, val2}; alias none;
    }
```

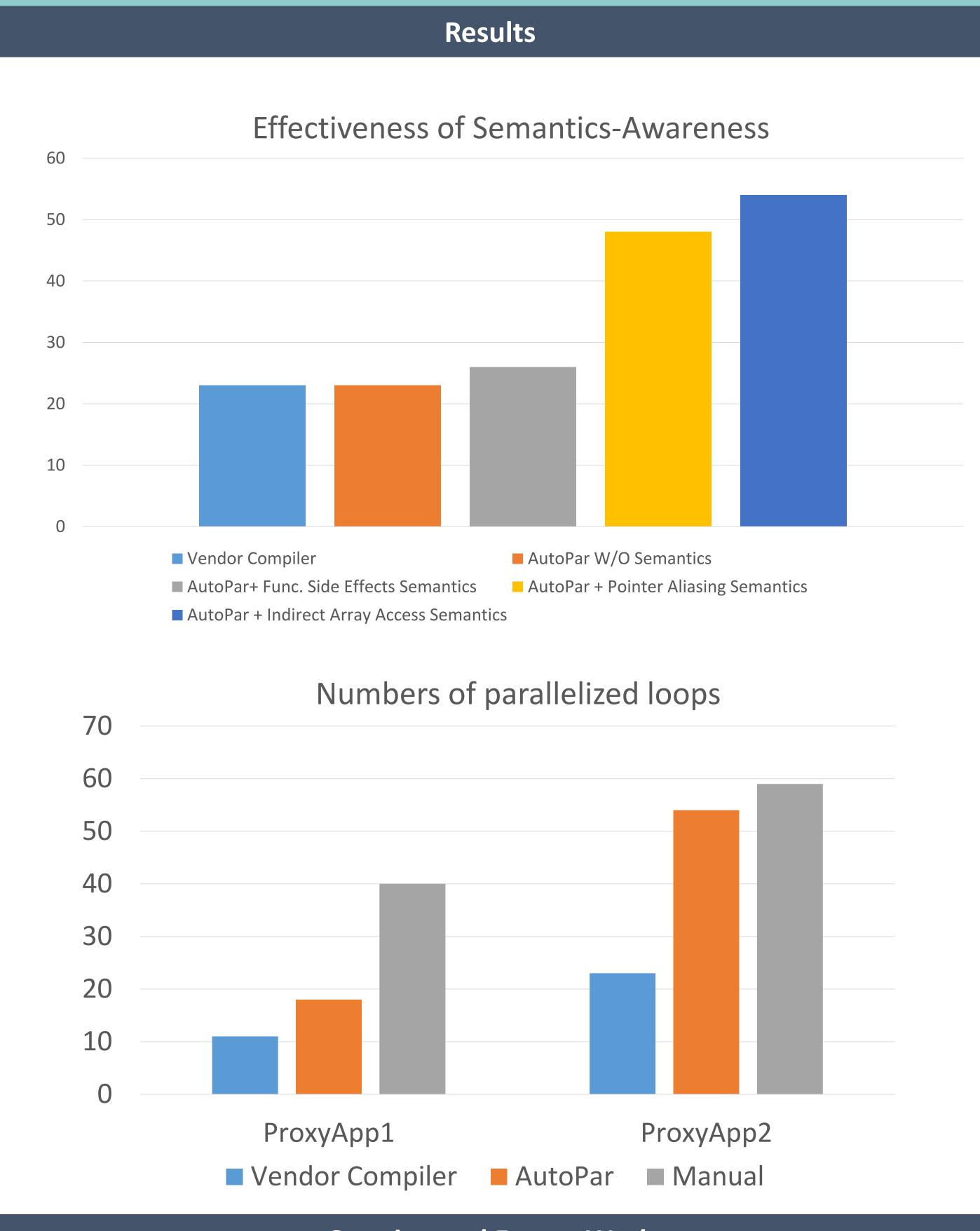
An example semantics specification file



Before	After
void interpolate1D(void interpolate1D(class floatArray
class floatArray &fineGrid,	&fineGrid, class floatArray &coarseGrid)
class floatArray &coarseGrid)	{
{	#pragma omp parallel for private (i)
•••	firstprivate (_var_0)
for (i = 1; i < _var_0; i += 1) {	for (i = 1; i <= _var_0 - 1; i += 1) {
fineGrid.elem(i) =fineGrid.elem(i)+1;	fineGrid.elem (i) = fineGrid.elem (i) + 1;
}	}
}	}

Additional features requested while working with LLNL application teams:

- 1. Undo loop normalization: users want their loops unchanged.
- 2. A helper tool to move variable declarations into innermost scopes: reducing the number of shared variables passed around
- 3. Generate patches instead of outputting lots of files with scattered changes
- 4. Support checking correctness of existing OpenMP directives
- 5. Verify correctness of generated OpenMP codes: using third party tools like Intel Inspector to catch data races. User-provided semantics can be wrong.



Ongoing and Future Work

- Standardize the semantics representation: ontology-based formats (OWL, JSON-LD)
- Support linearized array access: a[c1*i+c2*j+c3], often subscript terms are calculated separately in advance
- Incorporate profitability analysis: parallelizable → worth parallelizing
- Generate OpenMP 4.x directives for GPUs
 More info: http://rosecompiler.org/ROSE_HTML_Reference/auto_par.html